

### Features:

Power supply

- single wide VME module, compatible with VME64 and VME64x crates.
   only uses VME power supply of +5V (max 4.5A) and +12V (max 1.5A).
- Supplies up to 16 MUX-16 devices on up to 4 MUX-buses (up to 40W total).

### MUX-bus

- Bus length up to 3 m.
- 4 MUX-buses, two of them on the motherboard behind the front connectors.
- 1 mesytec control bus can control up to 16 devices on 4 buses.
- 4 Lemo IOs for trigger signals / control bus.
  Every two share half of the Cbus address space.

### MADC-32 interface

- Ored trigger output from 4 buses to start MADC-32.
- 4 bus outputs with two amplitudes and two positions are available on MADC-32 compatible 32pin header connector.
- Output voltage for 4V MADC-32 range.



### **Bus rules:**

- 1) Bus 0: buses joined to connector A and B (sub buses) must not have MUX-16 devices with the same address, set at address coders.
- 2) Maximum 8 MUX-16 devices may be added to one Bus (distribution to sub bus A/B may be unequal).

Note that amplitude coding for position, is shifted with address coder setting.

## **Required power:**

No load:

+ 5V	+ 150 mA
+ 12V	+ 80 mA
- 12V	+ 40 mA

With 16x MUX-16-devices connected:

+ 5V + 4.5A + 12V + 1.5A - 12V - 40 mA

# Maximum load for a crate with 192 MUX-16 devices supplied

VME-Crate filled with 12 MUXD drivers with 16x MUX-16 on each + 6x MADC-32

+ 5V	+ 55A
+ 12V	+ 20A
- 12V	- 1A

mesytec GmbH & Co. KG Wernher-von-Braun-Str. 1, D-85640 Putzbrunn, Germany phone: +49 – 89 / 456007-30 fax: +49 – 89 / 456007-39 info@mesytec.com – www.mesytec.com

# Example

Setup for 16 MUX-16 devices, 1x MUXD-4 and one bank (16 channels) of MADC-32



At the Cbus Connection an MRC-1 remote controller module is connected. Bus 0 (A/B) show the addresses set at the MUX dial. For bus 1 the addresses are shifted up by 8, resulting in an address range for both buses of 0 to 15.

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## A second way to control the MUX devices is via VME-bus.

### **Mesytec control bus**

MRC	Module RC				
0x00	rc_busno	2	RW	0	Always = $0$ is external bus. Can not be changed
0x02	rc_modnum	4	RW	0	015 (module ID set with hex coder at external module)
					(07 at low bus, 815 at high bus)
0x04	rc_opcode	7	RW		$3 = RC_on, 4 = RC_off, 6 = read_id,$
					16 = write_data, 18 = read_data
0x06	rc_adr	8	RW		module internal address, see box below
0x08	rc_dat	16	RW		data (send or receive), write starts sending
0x0A	send return	4	R		bit $0 = active$
	status				bit $1 = address collision$
					bit 2 = no response from bus (no valid address)

Send time is 400 us. Wait that fixed time before reading response or sending new data. Also polling at 0x0A for bit 0 = 0 is possible

The LEDs on Trigger IOs show traffic ont the control bus lines.

# **Example for controlling MUX modules**

MUX internal Address	Function	
0	Deactivate trigger: 1= deactivated, 0= normal operation	
1	Set Polarity: 0= positive charge at input, 1= negative charge.	
2	Set Range: 0= lowest gain, 7 = highest gain.	
3	Set Threshold; 04095 (4095 corresponds to 80% of selected full range)	
Intrinsic bus commands are RC on/off and read ID		

Initialise and read out a MUX-16 module.

MUX-16 on bus 0, ID-coder set to 7

Connected bus lines must be terminated at the MUX device. Unconnected ones may be left open.

Write(16)	addr 0x02 data 7	// address module 7
Write(16)	addr 0x04 data 16	// send code "write"
Write(16)	addr 0x08 data 3	// module internal address: 3=threshold.
Write(16)	addr 0x08 data 1024	// threshold value = 1024 (20% full range)

#### Activate RC in module

All set data will get active. This can also be done before setting the values.

Write(16)	addr 0x02 data 7	// address module 7
Write(16)	addr 0x04 data 3	// send code "RC_on"
Write(16)	addr 0x08 data 0	// initialise send request. Data has no effect